

Timeout Programming

Last updated 6/10/21

Timeout Programming

- Timeout Operation
 - Nucleo-L476RG has 12 timers
 - It's not clear how many of these can be used in our implementation
- The Timeout uses ISRs
 - All usual ISR rules apply
- Timeout runs once

Timeout Programming

- Timeout Connections
 - There are no connections enabled in the Mbed system

Timeout Programming

- Timeout Class

| Public Member Functions | | |
|-------------------------|---|---|
| template<typename F > | | |
| MBED_FORCEINLINE void | <code>attach (F &&func, float t)</code> | Deprecated |
| | Attach a function to be called by the Ticker , specifying the interval in seconds. More... | |
| void | <code>attach (Callback< void()> func, std::chrono::microseconds t)</code> | Use 10us, 10ms, 10s not 10, 10000, ... |
| | Attach a function to be called by the Ticker , specifying the interval in microseconds. More... | |
| void | <code>attach_us (Callback< void()> func, us_timestamp_t t)</code> | Deprecated |
| | Attach a function to be called by the Ticker , specifying the interval in microseconds. More... | |
| void | <code>detach ()</code> | |
| | Detach the function. More... | |

Timeout Programming

- Constructors - template

Public Member Functions

```
template<typename F >
```

```
// Create Timeout object  
Timeout TO_1;
```


Timeout Programming

- Member Functions (Methods)

| | | |
|------------------------------------|---|---|
| <code>MBED_FORCEINLINE void</code> | <code>attach (F &&func, float t)</code> | Deprecated |
| | Attach a function to be called by the Ticker , specifying the interval in seconds. More... | |
| <code>void</code> | <code>attach (Callback< void()> func, std::chrono::microseconds t)</code> | Use 10us, 10ms, 10s not 10, 10000, ... |
| | Attach a function to be called by the Ticker , specifying the interval in microseconds. More... | |
| <code>void</code> | <code>attach_us (Callback< void()> func, us_timestamp_t t)</code> | Deprecated |
| | Attach a function to be called by the Ticker , specifying the interval in microseconds. More... | |
| <code>void</code> | <code>detach ()</code> | |
| | Detach the function. More... | |

```
// Attach the function to call when the timeout count is reached
TO_1.attach(&my_to, 1000us);
```

Timeout Programming

- Simple example
 - Setup a simple timeout

```
////////////////////////////////////
//
// timeout_class_ex_1 project
//
// created 6/4/21 by tj
// rev 0
//
////////////////////////////////////
//
// Timeout example file for class
//
// shows basic timeout operation
//
////////////////////////////////////

#include "mbed.h"
#include <stdio.h>

// function prototypes (actually an ISR)
void my_to(void);

// Global HARDWARE Objects
// Create digital output to drive with the timeout (ISR)
DigitalOut Out_dig(D4);
// Create Timeout object
Timeout TO_1;

int main(void){
    setbuf(stdout, NULL); // disable buffering

    // splash
    printf("\n\ntimeout_class_ex_1 - example for EE2905\n");
    printf("Using Mbed OS version %d.%d.%d\n",
           MBED_MAJOR_VERSION, MBED_MINOR_VERSION, MBED_PATCH_VERSION);

    // toggle the output for a reference
    Out_dig = 1;
    wait_us(200);
    Out_dig = 0;
    wait_us(200);

    // toggle the output just prior to starting the timeout object
    Out_dig = 1;

    // Attach the function to call when the timeout count is reached
    TO_1.attach(&my_to, 1000us);
}
```

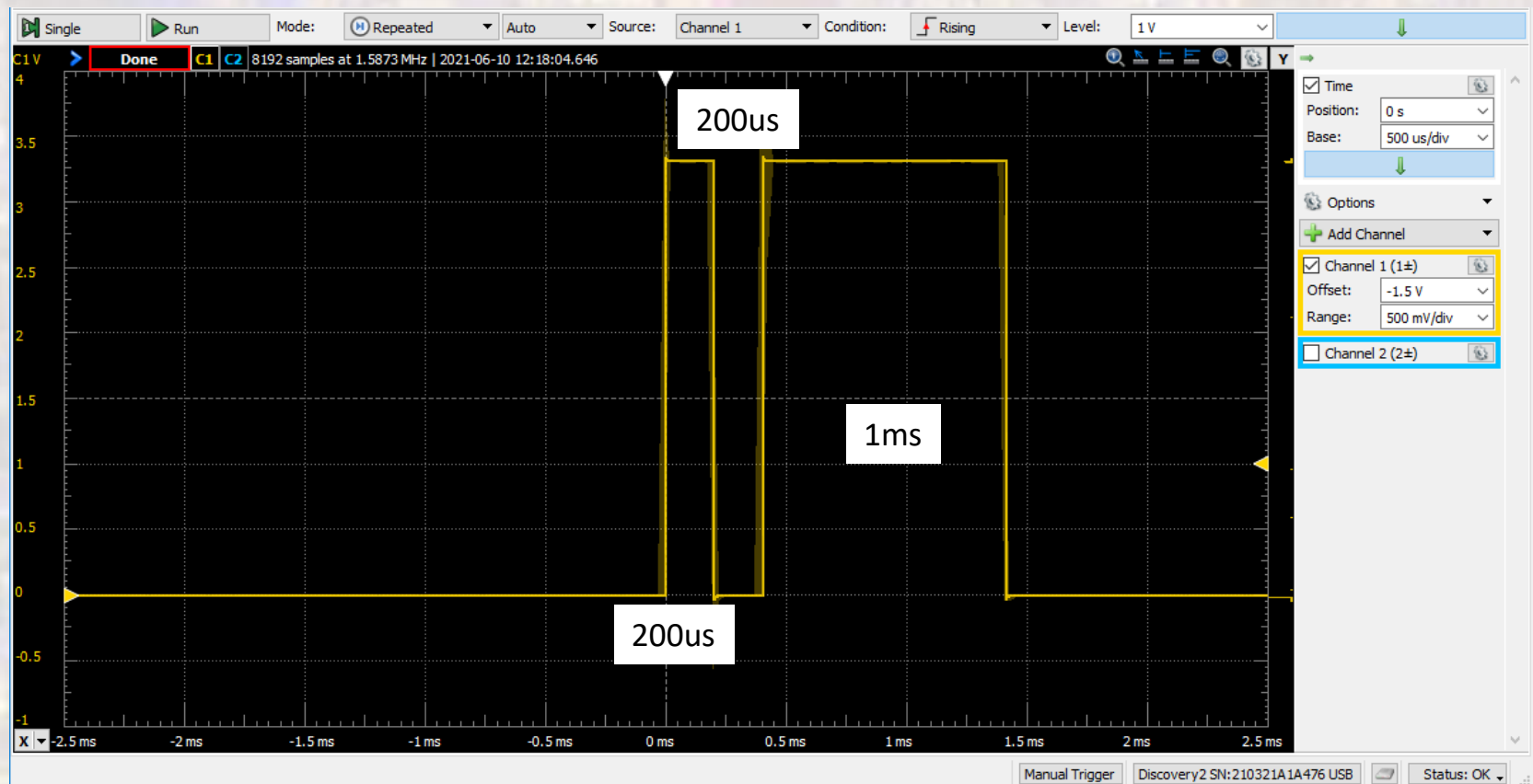
```
// create a wait loop
while(1){
    wait_us(10000);
} // end while

return 0;
} // end main
```

```
void my_to(void){
    Out_dig = !Out_dig;
} // end my_tick
```

Timeout Programming

- Simple example
- Setup a simple timeout



Timeout Programming

- Limitations summary
 - Minimum measurable timer tick is 1 μ s