

Hazard - Checkoff

- LCD operational
- Line sensors operational
- Bot reacting to line sensors
 - Run your bot for 2 minutes inside the ring
 - When at edge, stop and turn, then continue
 - You must run fast enough to encounter the edge of the ring at least 5 times
 - Your LCD must display your current motion
 - straight forward
 - straight reverse
 - left forward
 - left reverse
 - right forward
 - right reverse
 - stopped