

# Accelerometer Intro

Last updated 6/6/20

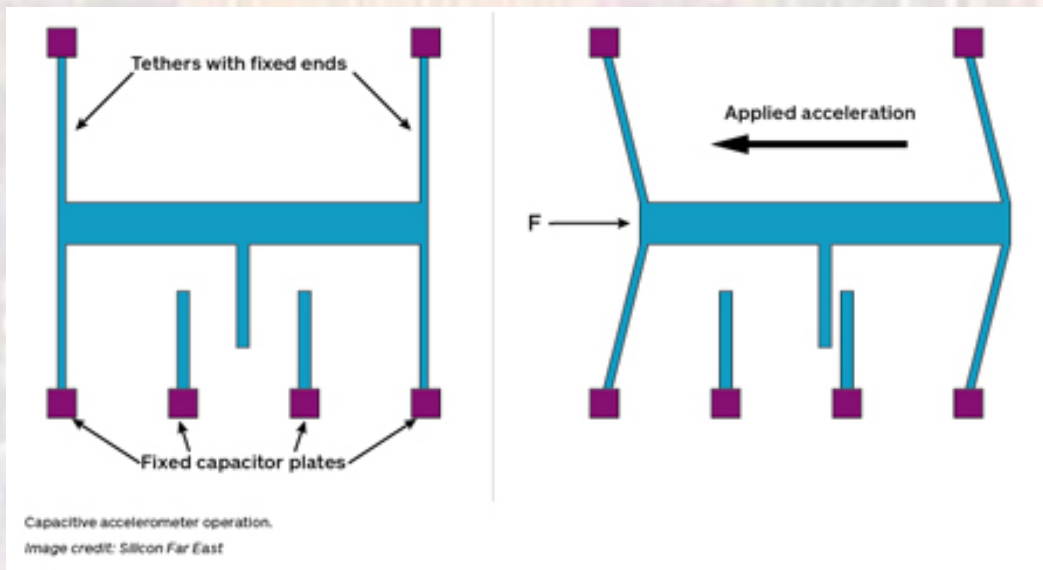
# Accelerometer Intro

These slides review the operation of an  
Accelerometer

Upon completion: You should be able to describe  
and operation of an Accelerometer

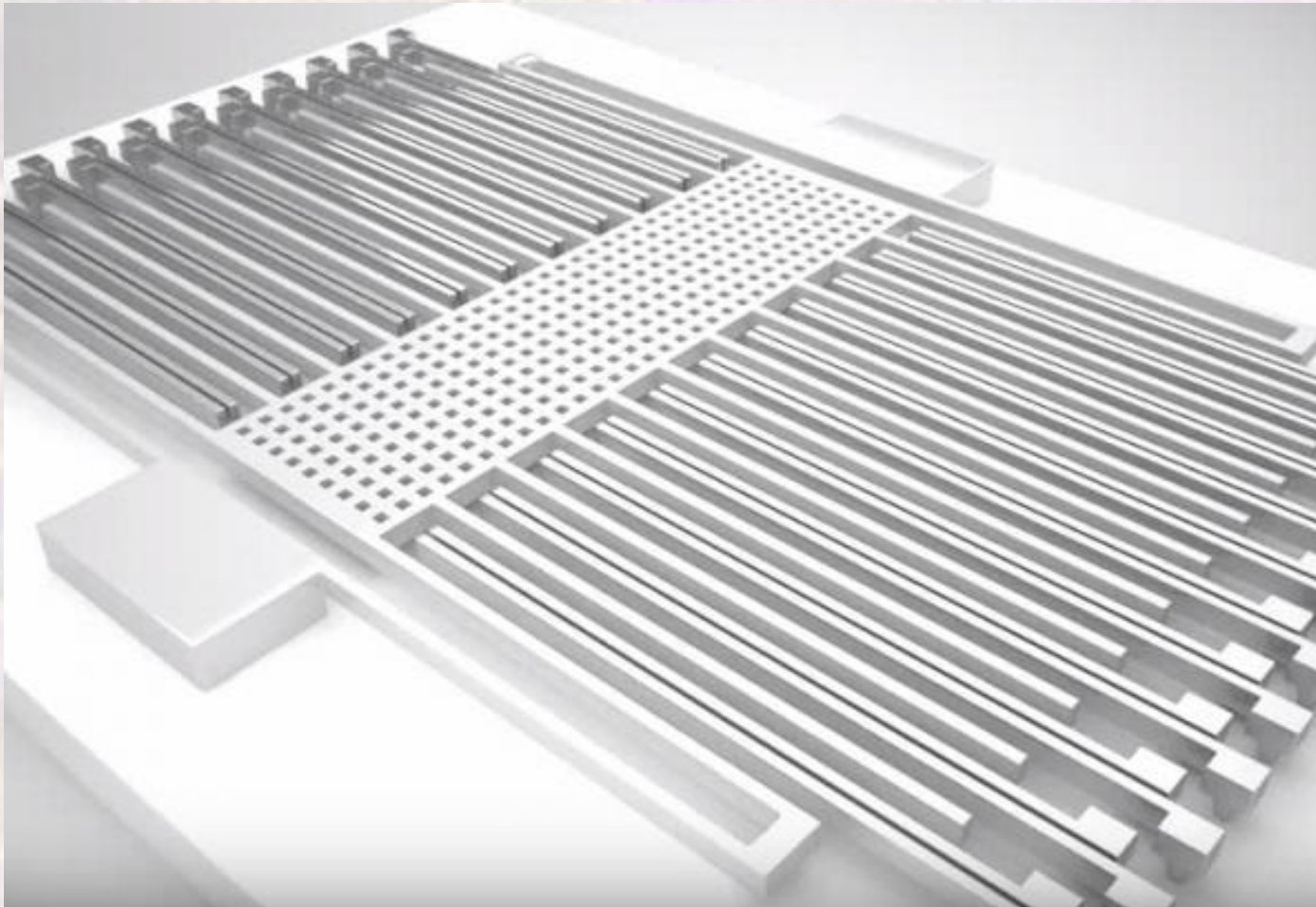
# Accelerometer Intro

- Basic Accelerometer Operation
  - Suspend a conductive mass from fixed points
  - Interleave fixed conductors
  - Acceleration  $\rightarrow$  movement of the suspended mass  $\rightarrow$  changes in relative capacitance between the suspended conductors and the fixed conductors



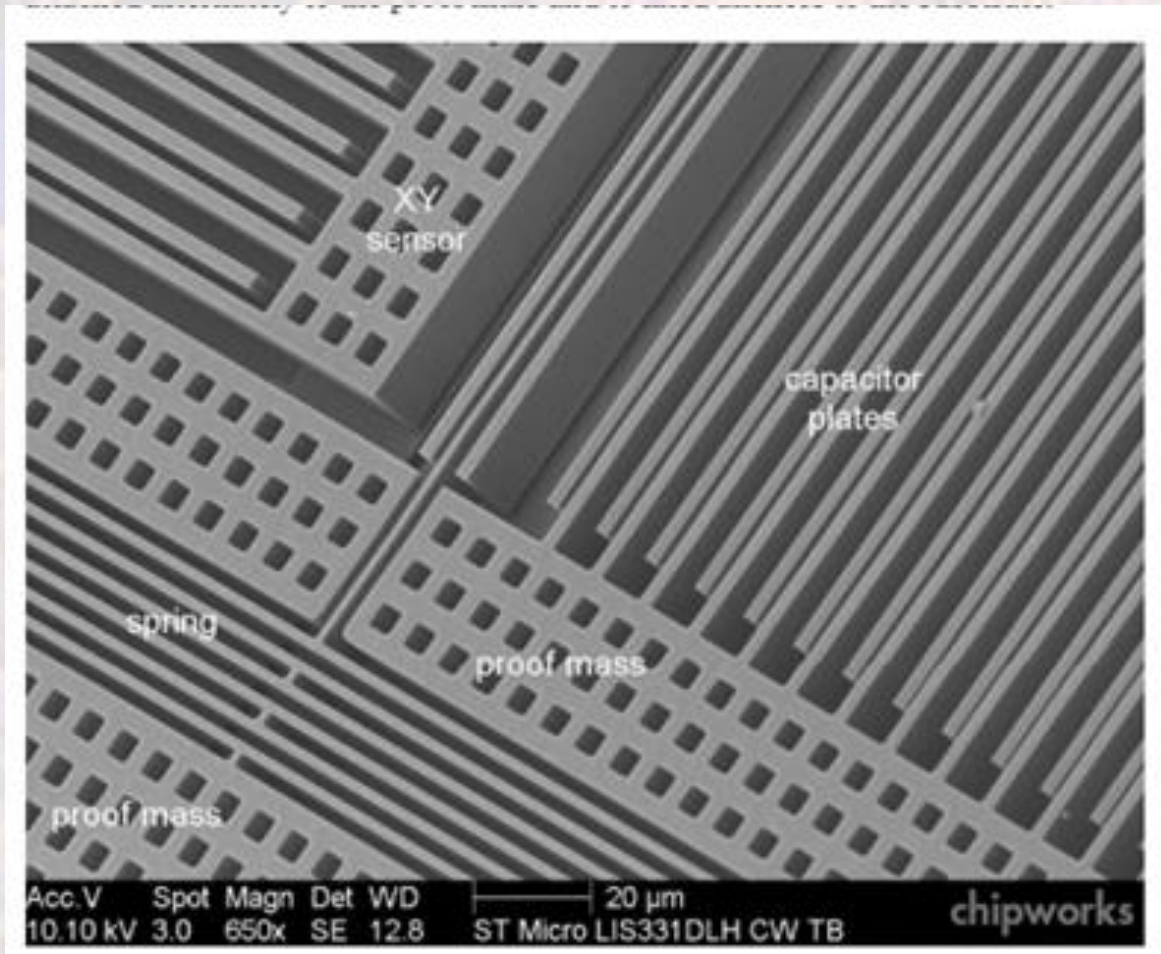
# Accelerometer Intro

- Single Axis



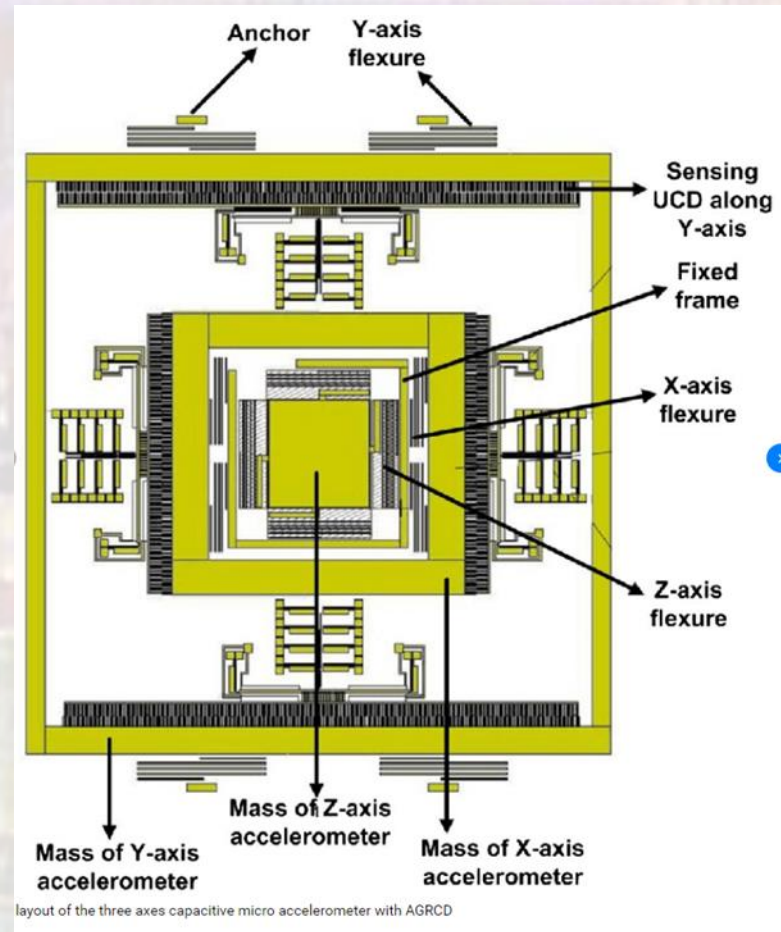
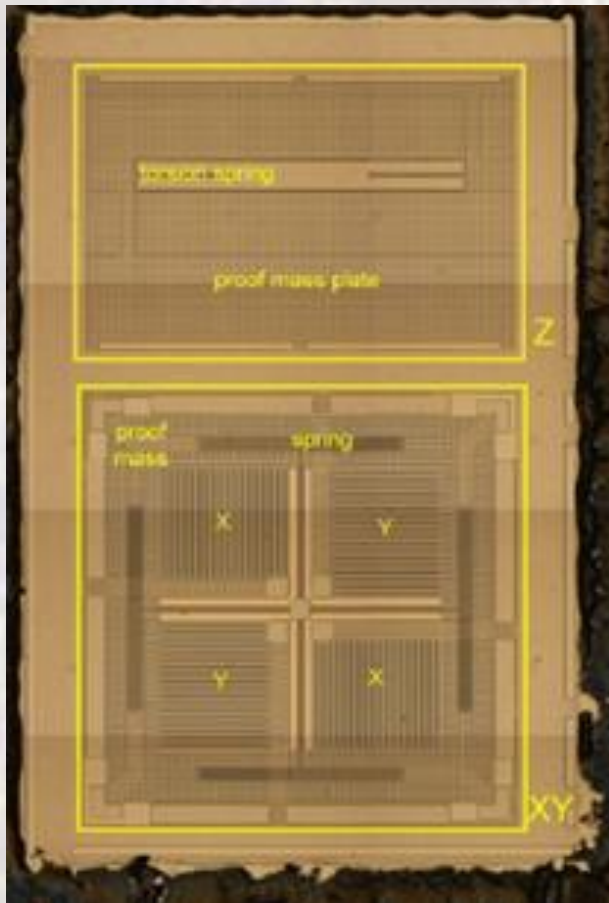
# Accelerometer Intro

- Dual Axis



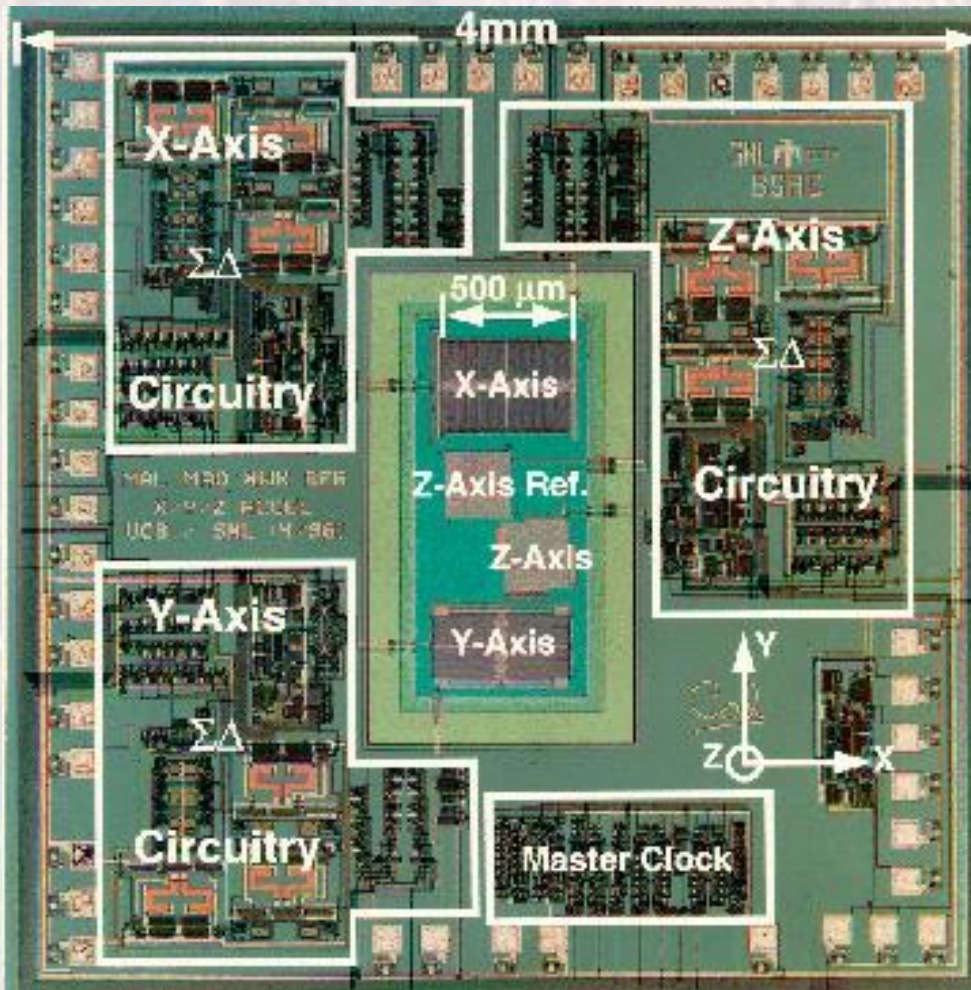
# Accelerometer Intro

- 3-Axis



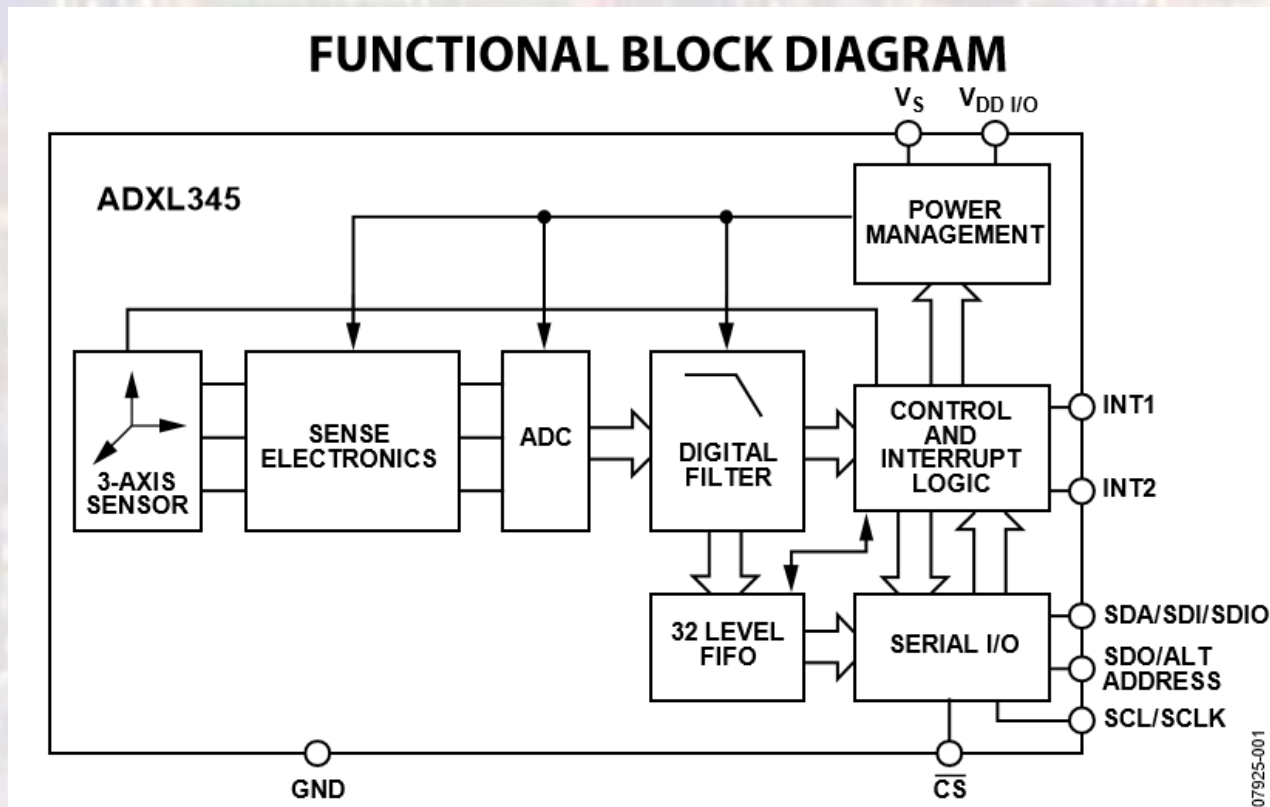
# Accelerometer Intro

- Integrated electronics



# Accelerometer Intro

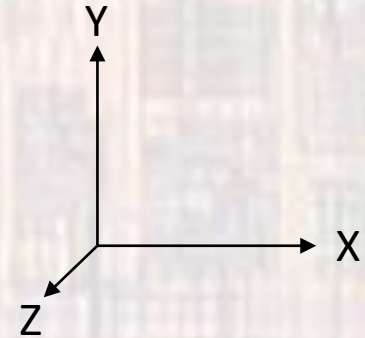
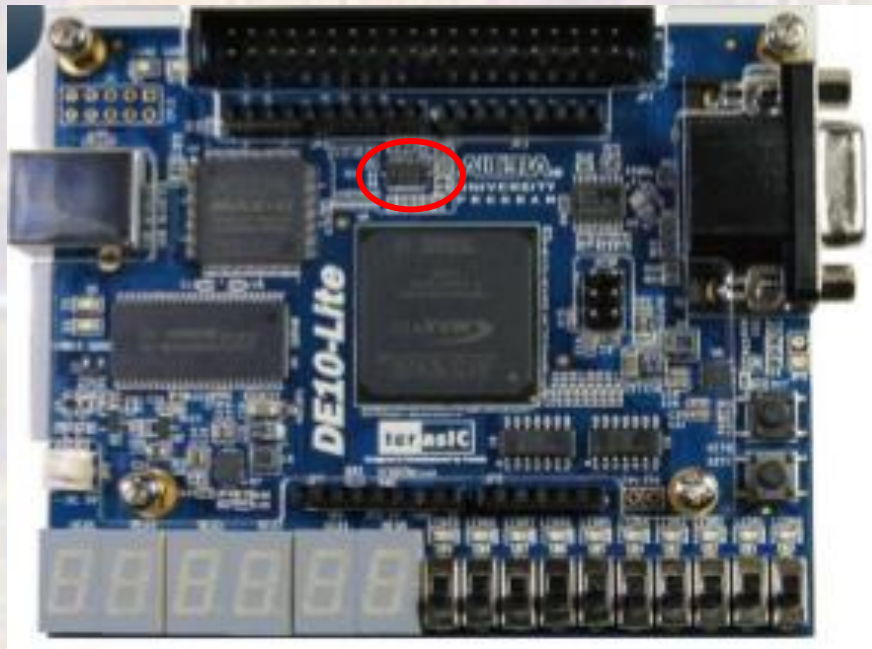
- ADXL345 – 3-axis Accelerometer
  - I2C and SPI interfaces
  - FIFO sample storage





# Accelerometer Intro

- ADXL345 – 3-axis Accelerometer
  - Selectable  $\pm 2$ ,  $\pm 4$ ,  $\pm 8$ ,  $\pm 16$  g measurement range
  - 10bit resolution: 4.3mg/LSB -34.5mg/LSB
  - Up to 3200Hz data rate



# Accelerometer Intro

- ADXL 345 Default modes
  - 4 wire SPI
  - 10bit
  - Data: right justified, sign extended
  - +/- 2g range
  - Trigger on int1

# Accelerometer Intro

- Limitations

$$a = \frac{dv}{dt} \quad dv = a dt \quad v = \int a dt \quad v = at + c \quad v = at + v_0$$

$$v = \frac{dx}{dt} \quad dx = v dt \quad x = \int v dt \quad x = \int (at + v_0) dt \quad x = \frac{1}{2}at^2 + v_0t + c$$

$$x = \frac{1}{2}at^2 + v_0t + x_0$$

$$x = \int \int a_x dt^2$$