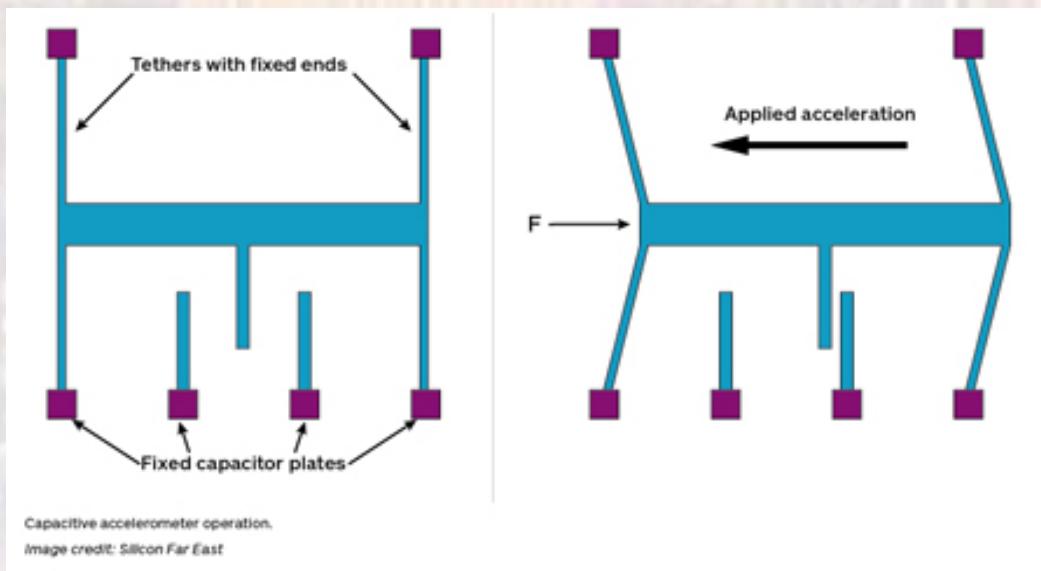


Accelerometer Intro

Last updated 7/21/23

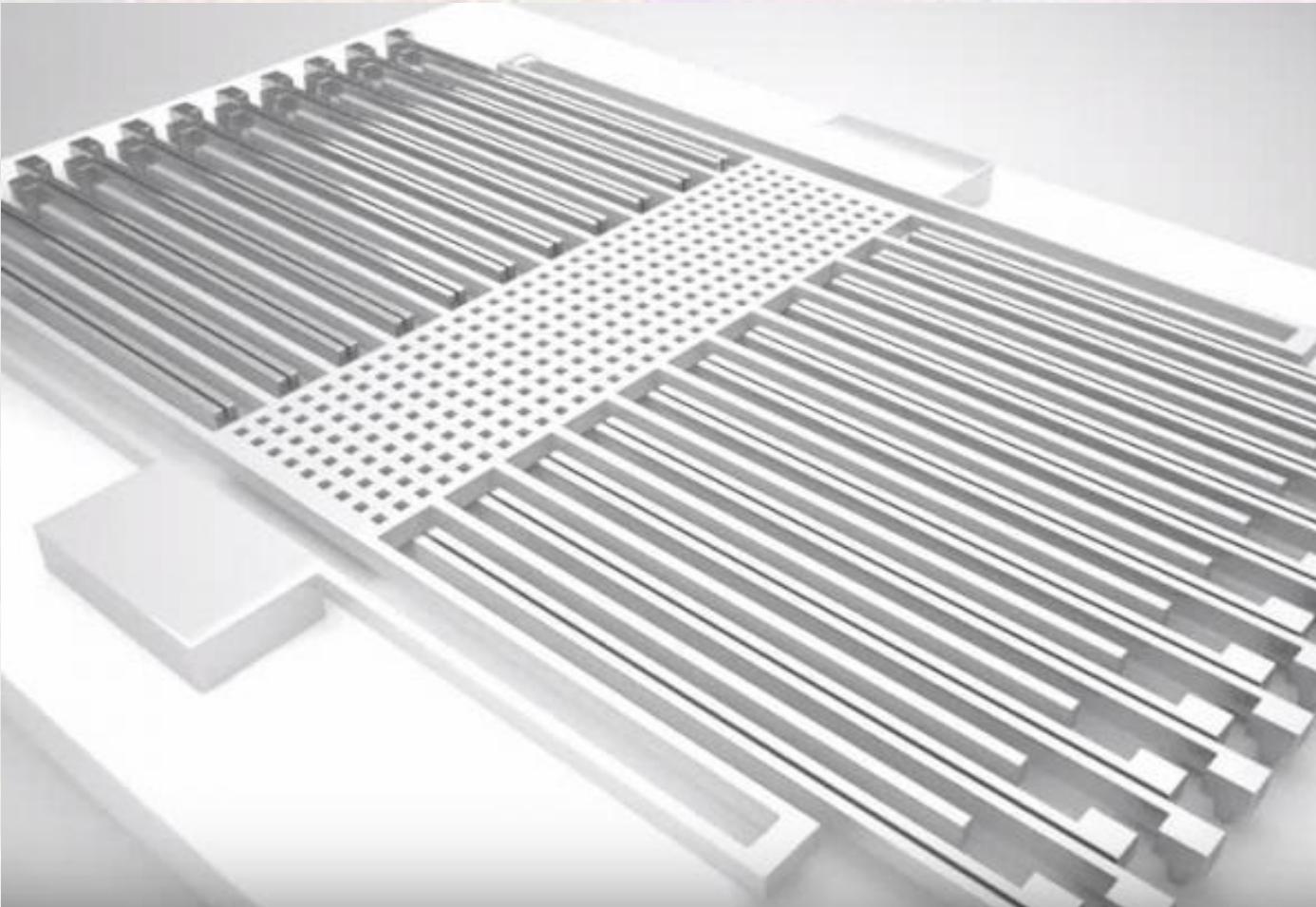
Accelerometer Intro

- Basic Accelerometer Operation
 - Suspend a conductive mass from fixed points
 - Interleave fixed conductors
 - Acceleration → movement of the suspended mass → changes in relative capacitance between the suspended conductors and the fixed conductors



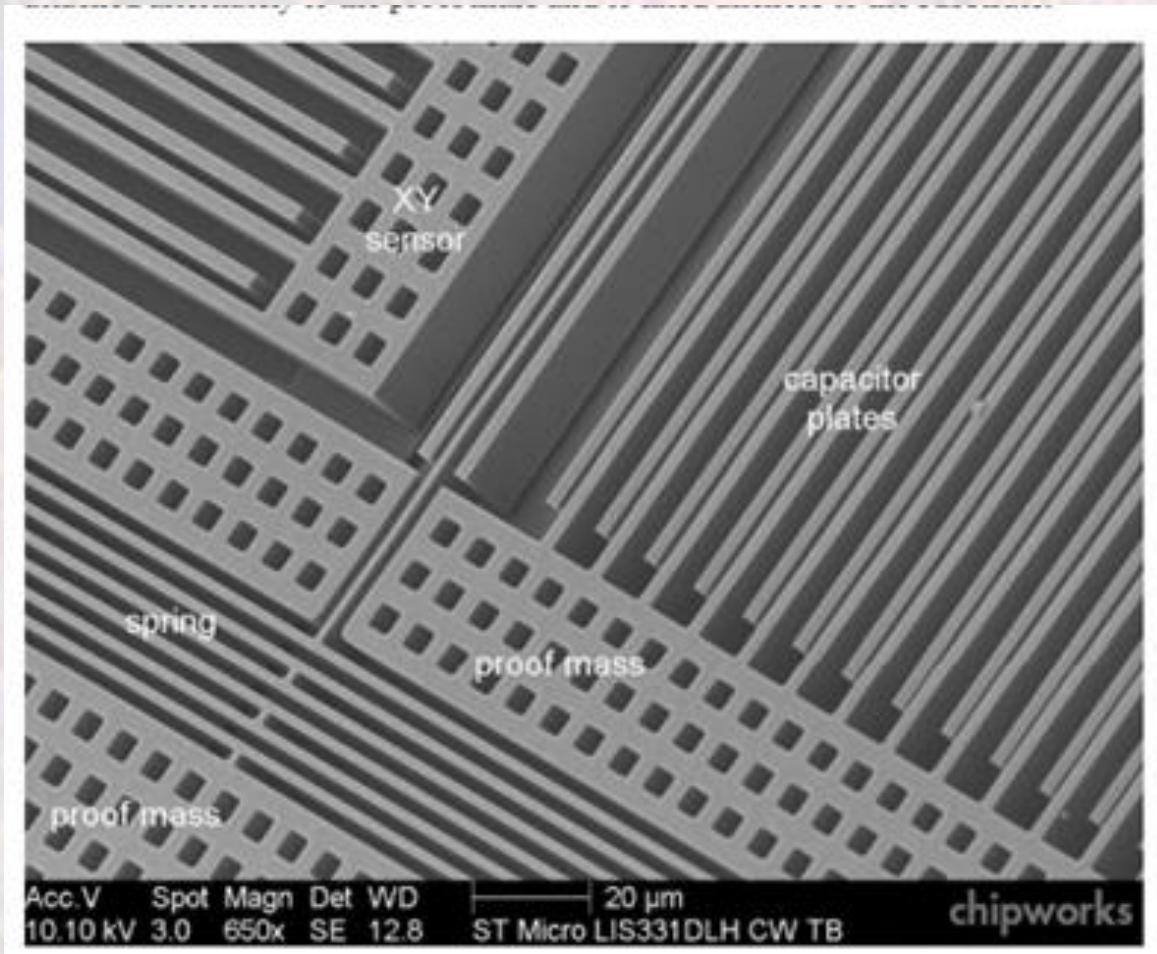
Accelerometer Intro

- Single Axis



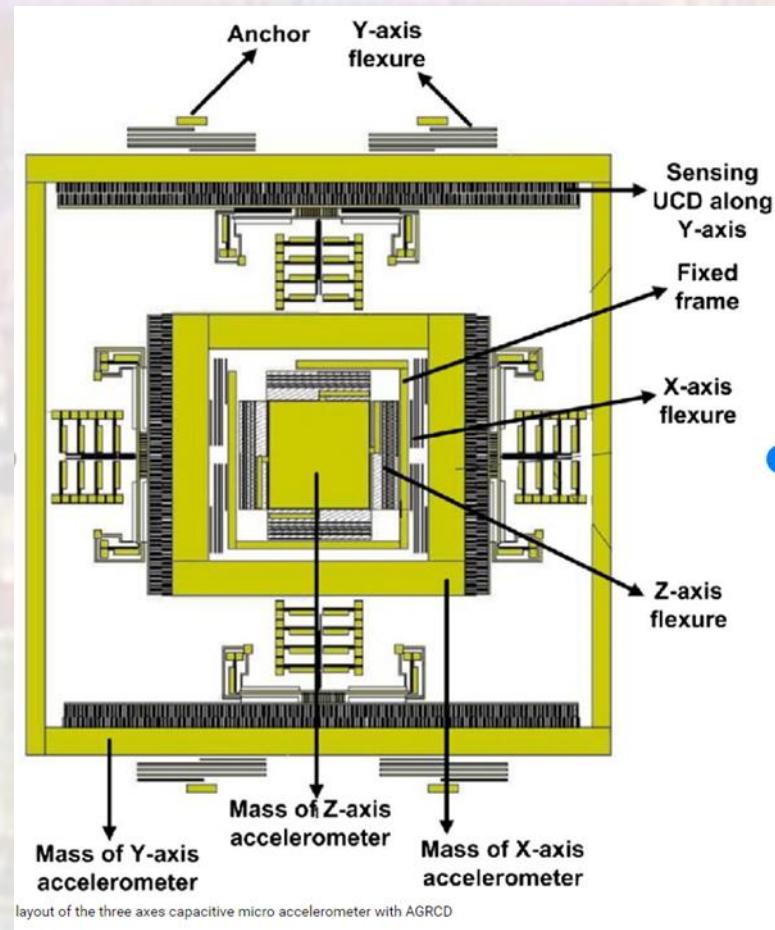
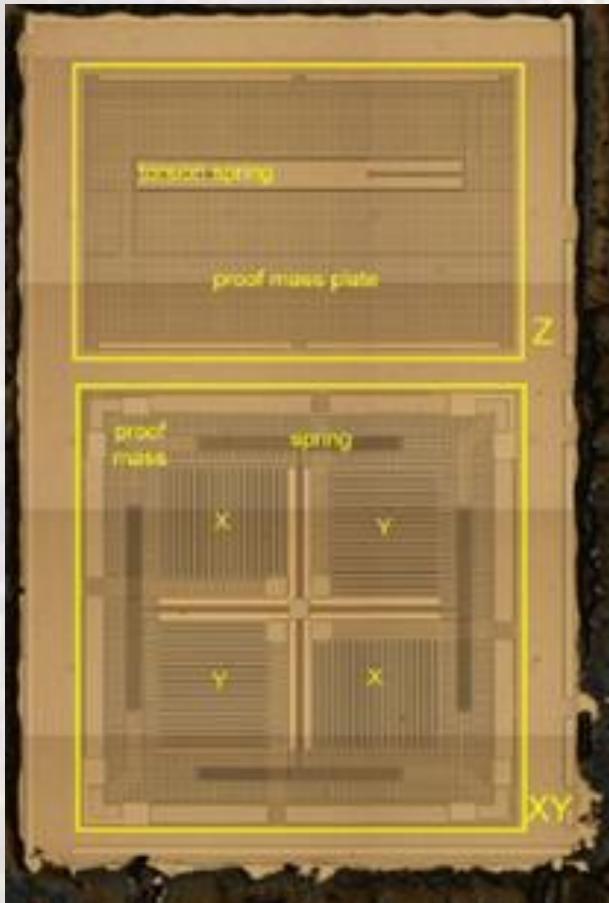
Accelerometer Intro

- Dual Axis



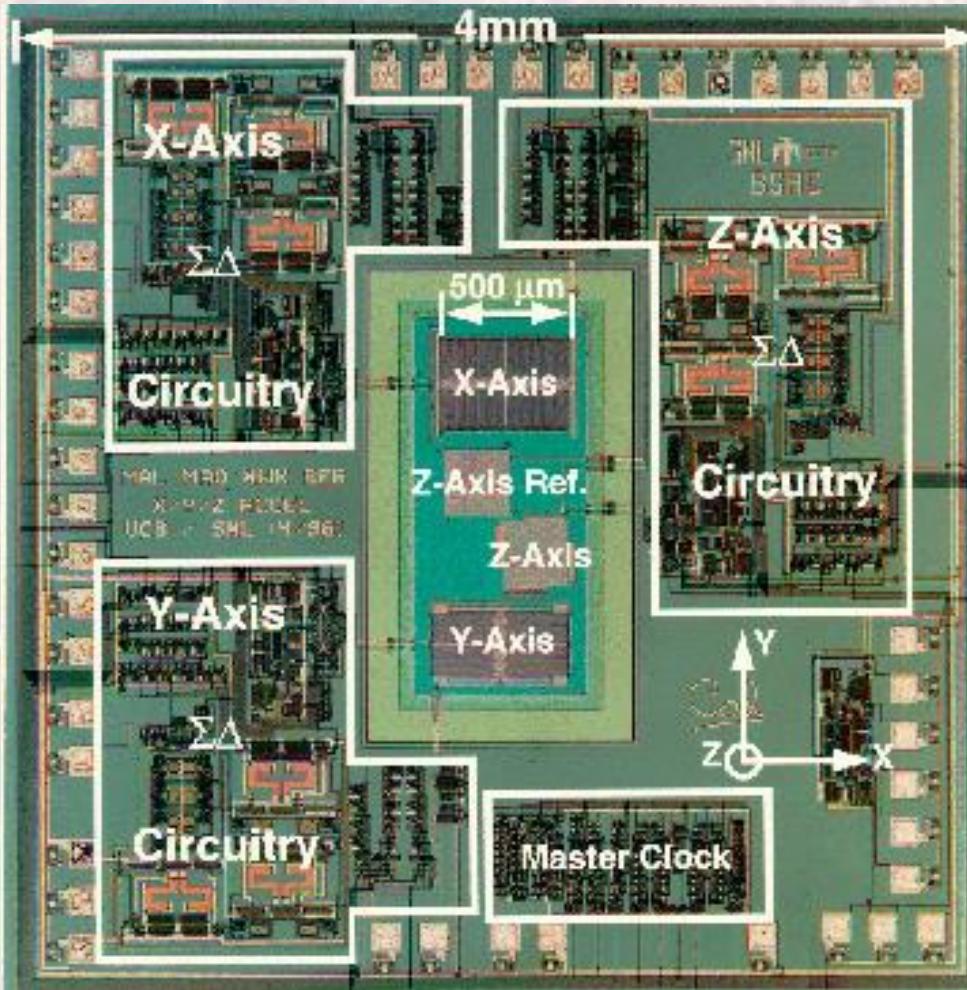
Accelerometer Intro

- 3-Axis



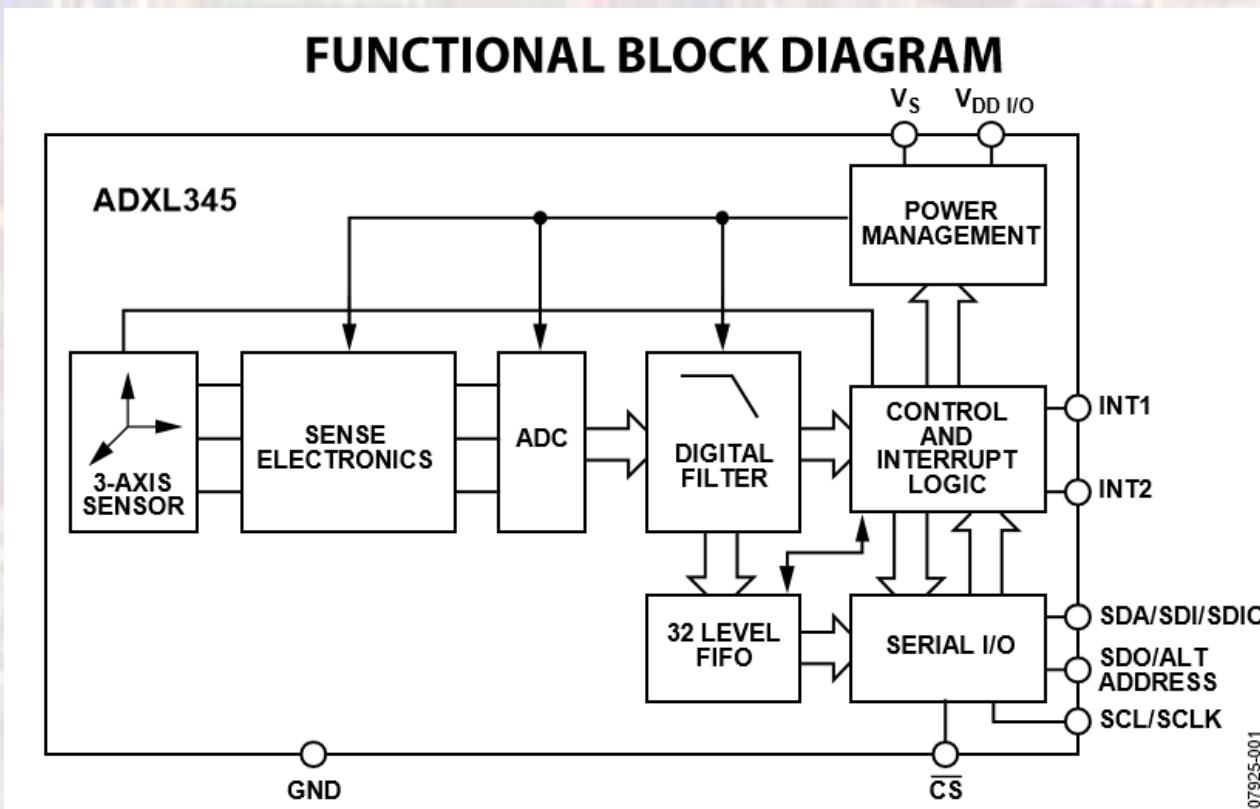
Accelerometer Intro

- Integrated electronics



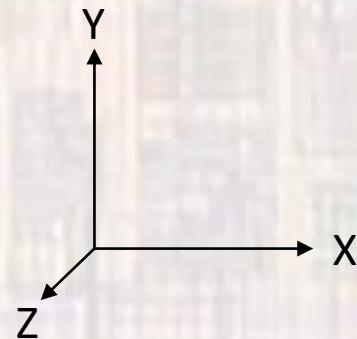
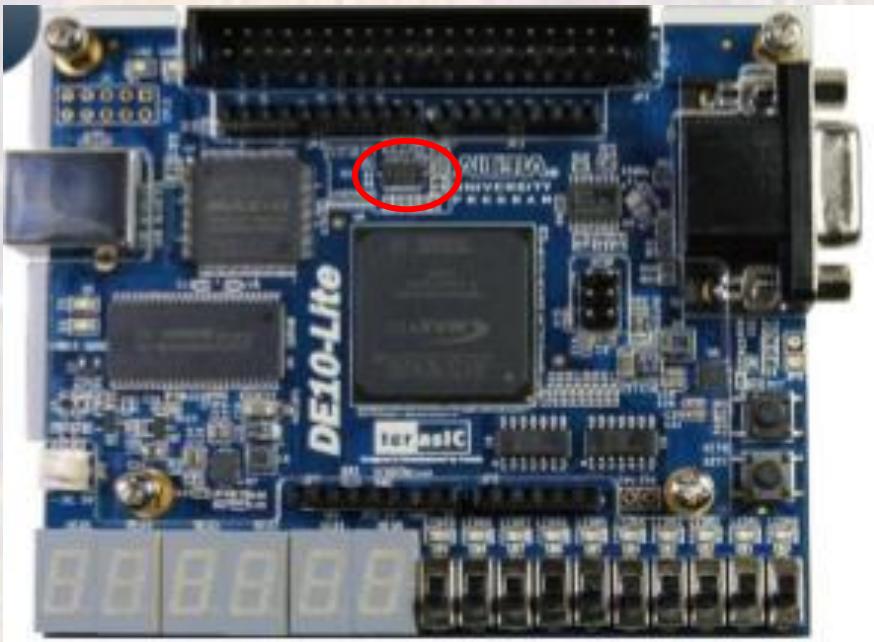
Accelerometer Intro

- ADXL345 – 3-axis Accelerometer
 - I₂C and SPI interfaces
 - FIFO sample storage



Accelerometer Intro

- ADXL345 – 3-axis Accelerometer
 - Selectable $\pm 2, \pm 4, \pm 8, \pm 16$ g measurement range
 - 10bit resolution: 4.3mg/LSB - 34.5mg/LSB
 - Up to 3200Hz data rate



Accelerometer Intro

- ADXL 345 Default modes
 - 4 wire SPI
 - 10bit
 - Data: right justified, sign extended
 - +/- 2g range
 - Trigger on int1

Accelerometer Intro

- Limitations

$$a = \frac{dv}{dt} \quad dv = a \, dt \quad v = \int a \, dt \quad v = at + c \quad v = at + v_0$$

$$v = \frac{dx}{dt} \quad dx = v \, dt \quad x = \int v \, dt \quad x = \int (at + v_0) \, dt \quad x = \frac{1}{2}at^2 + v_0t + c$$

$$x = \frac{1}{2}at^2 + v_0t + x_0$$

$$x = \int \int a_x \, dt^2$$