## Optimized State Diagrams

## Last updated 7/18/23

## Optimized State Diagrams

- Two formal approaches for optimization
- Successive Partitions
- Implication Chart


## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State |
| :---: | :---: | :---: |
| A | 0 | B |
| A | 1 | C |
| B | 0 | D |
| B | 1 | F |
| C | 0 | F |
| C | 1 | E |
| D | 0 | B |
| D | 1 | G |
| E | 0 | F |
| E | 1 | C |
| F | 0 | E |
| F | 1 | D |
| G | 0 | F |
| G | 1 | G |


| State | Output |
| :---: | :---: |
| A | 1 |
| B | 1 |
| C | 0 |
| D | 1 |
| E | 0 |
| F | 0 |
| G | 0 |


| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States | Action |
| :--- | :---: | :--- |
| P0 | ABCDEFG |  |
|  | 1101000 |  |

Identify states and outputs

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States | Action |
| :--- | :---: | :--- |
| PO | ABCDEFG |  |
| 1101000 | Separate |  |

Partition into sets with same outputs

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States | Action |
| :--- | :---: | :--- |
| P0 | ABCDEFG <br> 1101000 | Separate <br> ABD, CEFG |
| P1 | ABD | CEFG |

Identify next states based on current state and inputs

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States | Action |
| :---: | :---: | :---: |
| PO | $\begin{aligned} & \text { ABCDEFG } \\ & 1101000 \end{aligned}$ | Separate ABD, CEFG |
| $\begin{aligned} & \text { P1 } \\ & \text { ln=0 } \\ & \text { ln }=1 \end{aligned}$ |  | Separate CEG and F |

Separate those groups by current state

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States |  |  | Action |
| :---: | :---: | :---: | :---: | :---: |
| PO | ABCDEFG <br> 1101000 |  |  | Separate ABD, CEFG |
| $\begin{aligned} & \text { P1 } \\ & \mathrm{In}=0 \\ & \mathrm{ln}=1 \end{aligned}$ | $\begin{aligned} & \text { ABD } \\ & \text { BDB } \\ & \text { CFG } \end{aligned}$ |  |  | Separate CEG and F |
| $\begin{aligned} & \text { P2 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | $\begin{aligned} & \text { ABD } \\ & \text { BDB } \\ & \text { CFG } \end{aligned}$ | $\begin{aligned} & \text { CEG } \\ & \text { FFF } \\ & \text { ECG } \end{aligned}$ | $\begin{aligned} & \text { F } \\ & \text { E } \\ & \text { D } \end{aligned}$ |  |

Identify next states based on current state and inputs

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |
|  |  |  |  |


| Partitions | Next States |  |  | Action |
| :---: | :---: | :---: | :---: | :---: |
| PO | $\begin{gathered} \text { ABCDEFG } \\ 1101000 \end{gathered}$ |  |  | Separate ABD, CEFG |
| $\begin{aligned} & \text { P1 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | $\begin{aligned} & \text { ABD } \\ & \text { BDB } \\ & \text { CFG } \end{aligned}$ | $\begin{aligned} & \text { CEFG } \\ & \text { FFEF } \\ & \text { ECDG } \end{aligned}$ |  | Separate CEG and F |
| $\begin{aligned} & \text { P2 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | $\frac{\uparrow}{\frac{\mathrm{ABD}}{\mathrm{BDB}}}$ | $\begin{gathered} \text { CEG } \\ \text { FFF } \\ \hline \text { ECG } \end{gathered}$ | $\begin{gathered} F \\ \text { E } \\ \text { D } \end{gathered}$ | Separate <br> $A D$ and $B$ |
|  | Identify any groups of next states that are not part of an existing partition |  |  |  |

Separate those groups by current state

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | O | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | O | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States |  | Action |  |
| :--- | :---: | :---: | :--- | :--- |
| P0 | ABCDEFG <br> 1101000 |  |  | Separate |

Identify next states based on current state and inputs

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |
|  |  |  |  |


| Partitions | Next States |  |  | Action |
| :---: | :---: | :---: | :---: | :---: |
| PO | $\begin{gathered} \text { ABCDEFG } \\ 1101000 \end{gathered}$ |  |  | Separate <br> ABD, CEFG |
| $\begin{aligned} & \text { P1 } \\ & \text { In }=0 \\ & \text { In }=1 \end{aligned}$ | Identify any groups of next states that are not part of an existing partition |  |  | eparate <br> EG and F |
| $\begin{aligned} & \text { P2 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | parate those gro BDB CFG | y curre FFF ECG | $\begin{gathered} \text { tate } \\ \mathrm{E} \\ \mathrm{D} \end{gathered}$ | Separate $A D$ and $B$ |
| $\begin{aligned} & \text { P2 } \\ & \ln =0 \\ & \ln =1 \end{aligned}$ | $A D$ $B$ <br> BB B <br> $C G$ $F$ | $\begin{gathered} \text { CEG } \\ \text { FFFF } \\ \hline \text { ECG } \end{gathered}$ | $\stackrel{F}{\mathrm{~F}} \mathrm{C}$ | No more reduction |

## Optimized State Diagrams

- Redundant / Equivalent States
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | O | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |


| Partitions | Next States |  |  |  | Action |
| :---: | :---: | :---: | :---: | :---: | :---: |
| PO | $\begin{gathered} \text { ABCDEFG } \\ 1101000 \end{gathered}$ |  |  |  | Separate <br> ABD, CEFG |
| $\begin{aligned} & \text { P1 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | $\begin{aligned} & \text { ABD } \\ & \text { BDB } \\ & \text { CFG } \end{aligned}$ |  | $\begin{aligned} & \text { CEFG } \\ & \text { FFEF } \\ & \text { ECDG } \end{aligned}$ |  | Separate <br> CEG and $F$ |
| $\begin{aligned} & \text { P2 } \\ & \text { ln }=0 \\ & \text { ln }=1 \end{aligned}$ |  |  | $\begin{gathered} \text { CEG } \\ \text { FFF } \\ \text { ECG } \end{gathered}$ | $\begin{aligned} & \text { F } \\ & \text { E } \\ & \text { D } \end{aligned}$ | Separate $A D$ and $B$ |
| $\begin{aligned} & \text { P2 } \\ & \text { In }=0 \\ & \text { ln }=1 \end{aligned}$ | $A D$ BB CG | $\begin{aligned} & \text { B } \\ & \text { D } \\ & \text { F } \end{aligned}$ | $\begin{gathered} \text { CEG } \\ \text { FFF } \\ \text { ECG } \end{gathered}$ | $\begin{aligned} & \text { F } \\ & \text { E } \\ & \text { D } \end{aligned}$ | No more reduction |
| Pfinal | AD | B | CEG | F |  |

## Optimized State Diagrams

- Redundant / Equivalent State
Partitions
PO
- Successive Partitions

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D |  |
| G | 0 | F | 0 |
| G | 1 | G | 0 |
|  |  | 0 |  |

7 states $\rightarrow 4$ states

| $P 1$ |
| :--- |
| In $=0$ |
| In $=1$ |
| $P 2$ |
| $\ln =0$ |
| $\ln =1$ |
| $P 2$ |
| In $=0$ |
| In $=1$ |
| Pfinal |
| Output |
| 1 |


| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: |
| AD | 0 | B | 1 |
| AD | 1 | CEG | 1 |
| B | 0 | AD | 1 |
| B | 1 | F | 1 |
| CEG | 0 | F | 0 |
| CEG | 1 | CEG | 0 |
| F | 0 | CEG | 0 |
| F | 1 | AD | 0 |
|  |  |  |  |


| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| $\mathbf{P}$ | 0 | Q | 1 |
| $\mathbf{P}$ | 1 | R | 1 |
| Q | 0 | P | 1 |
| Q | 1 | S | 1 |
| R | 0 | S | 0 |
| R | 1 | R | 0 |
| S | 0 | R | 0 |
| S | 1 | P | 0 |

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |



## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G |  |
|  |  |  |  |
|  |  |  |  |

compare pairs of states If outputs are different $X$ out box


## Optimized State Diagrams

## - Redundant / Equivalent States

- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F |  |
| G | 1 | G | 0 |
|  |  |  |  |

write in the implicants to all empty boxes The two states would be the same IFF the implicants are the same

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |

Traverse the structure and X out any boxes whose implicants are already X'd out This indicates the implicant is not true


A B C D E F G

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |

Traverse the structure and X out any boxes whose implicants are already X'd out This indicates the implicant is not true


A B C D E F G

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |

Traverse the structure and X out any boxes whose implicants are already X'd out This indicates the implicant is not true

$A B C D E F G$

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

Remaining un-X'd boxes indicate equivalent states

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |



## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |

Any duplicate entries indicate independent states

## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next <br> State | Output |
| :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |
| A | 1 | C | 1 |
| B | 0 | D | 1 |
| B | 1 | F | 1 |
| C | 0 | F | 0 |
| C | 1 | E | 0 |
| D | 0 | B | 1 |
| D | 1 | G | 1 |
| E | 0 | F | 0 |
| E | 1 | C | 0 |
| F | 0 | E | 0 |
| F | 1 | D | 0 |
| G | 0 | F | 0 |
| G | 1 | G | 0 |



## Optimized State Diagrams

- Redundant / Equivalent States
- Implication Chart

| State | Input | Next State | Output | 7 states $\rightarrow 4$ states |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| A | 0 | B | 1 |  |  |  |  |
| A | 1 | C | 1 |  |  |  |  |
| B | 0 | D | 1 |  |  |  |  |
| B | 1 | F | 1 |  |  |  |  |
| C | 0 | F | 0 | State | Input | Next | Output |
| C | 1 | E | 0 | AD |  | State |  |
| D | 0 | B | 1 |  | 0 | B | 1 |
| D | 1 | G | 1 | AD | 1 | CEG | 1 |
| E | 0 | F | 0 | B | 0 | AD | 1 |
| E | 1 | C | 0 | B | 1 | F | 1 |
| F | 0 | E | 0 | CEG | 0 | F | 0 |
|  |  |  |  | CEG | 1 | CEG | 0 |
| F | 1 | D | 0 |  |  |  |  |
| G | 0 | F | 0 | F | 0 | CEG | 0 |
| G | 1 | G | 0 | F | 1 | AD | 0 |
| ELE 3510 |  |  |  |  |  | 23 |  |



## - Design Process Circuit Design

1) Identify the states - collectively these make a state variable
2) Identify the Inputs and Outputs
3) Assign values for each input/output (encoding)
4) Create a state transition diagram / table
5) Optimize the state transition table
6) Assign values for the state variable for each state (encoding)
7) Create truth tables for the combinational logic blocks in the machine model: next state, output
8) Minimize the next state and output equations using K-maps or Boolean Algebra techniques
9) Draw the circuit schematic
10) Verify the solution
11) Build the physical circuit
12) Test the physical circuit to ensure correct operation

- Design Process HDL

1) Identify the states - collectively these make a state variable
2) Identify the Inputs and Outputs
3) Create a state transition diagram / table
4) Optimize the state transition table
5) Create the HDL to match the state transition table
6) Choose an encoding scheme (or let the tool decide)
7) Synthesize the design
8) Verify the solution
9) Build the physical circuit
10) Test the physical circuit to ensure correct operation
